

Uncertainty Quantification Methodologies for Climate Model Data with Discontinuities

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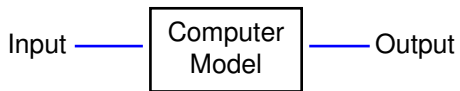
Uncertainties in Climate Modeling

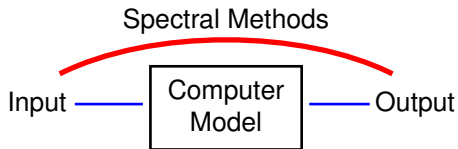
- Uncertainty sources
 - Parameter uncertainty
 - Model parameters
 - Initial/boundary conditions
 - Model geometry/structure
 - Model/structural uncertainty
 - Unknown physics
 - Reduced order models
 - Scenario uncertainty
 - Policy restrictions
 - Technology improvement
 - Intrinsic variability
 - Stochastic physics
 - Numerical errors

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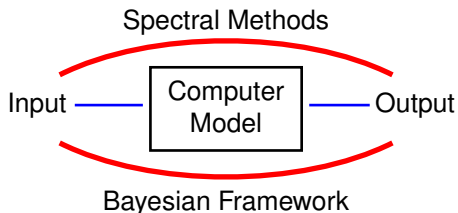
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- Need UQ for...
 - Model validation
 - Confidence assessment
 - Optimal design
 - Data assimilation

UQ components and methods

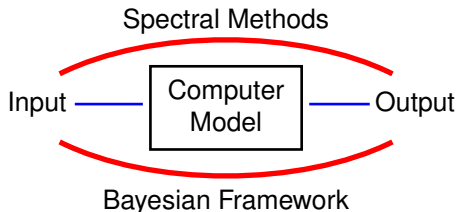




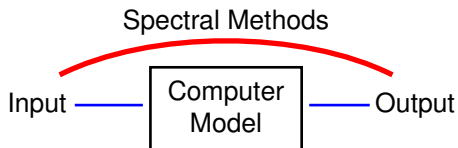
- Sensitivity analysis
 - Small parameter perturbations
- Predictability assessment
 - Larger parameter uncertainties



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- Parameter estimation
 - Inverse problems



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- Forward UQ methods
 - Direct (intrusive)
 - Derive new forward model
 - Intrusive Spectral Projection (ISP)
 - Sampling (non-intrusive)
 - Monte-Carlo, Quasi Monte-Carlo
 - **Non-intrusive Spectral Projection (NISIP)**

Polynomial Chaos expansion represents any random variable as a polynomial of a standard random variable

- Truncated PCE: finite dimension n and order p

$$X(\boldsymbol{\eta}) \simeq \sum_{k=0}^P c_k \Psi_k(\boldsymbol{\eta})$$

with the number of terms $P + 1 = \frac{(n+p)!}{n!p!}$.

- $\boldsymbol{\eta} = (\eta_1, \dots, \eta_n)$ standard i.i.d. r.v.
 Ψ_k standard orthogonal polynomials
 c_k spectral modes.
- Most common standard Polynomial-Variable pairs:
(continuous) Gauss-Hermite, Legendre-Uniform,
(discrete) Poisson-Charlier.

[Wiener, 1938; Ghanem & Spanos, 1991; Xiu & Karniadakis, 2002; Le Maître & Knio, 2010]

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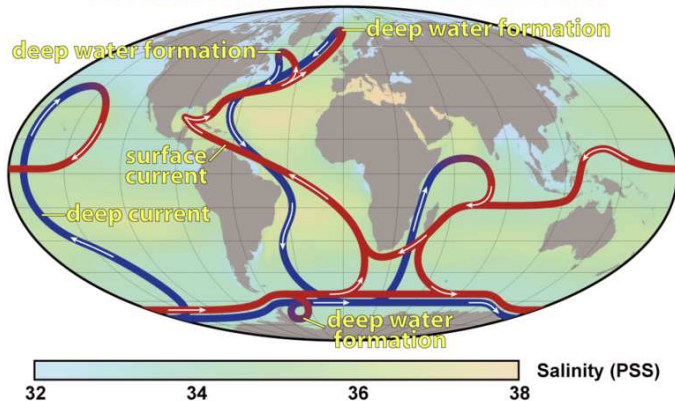
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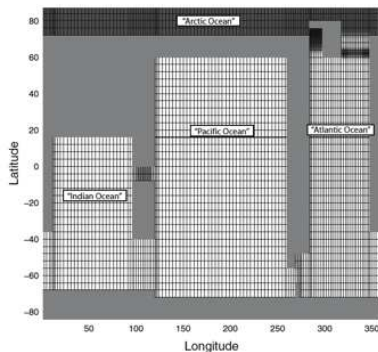
Meridional Overturning Circulation

Thermohaline Circulation

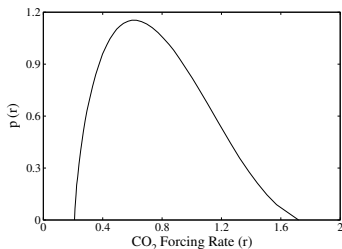


MOC transports heat from warm to cold regions

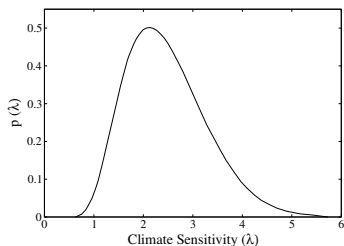
- **Computational model**
 - 3D Ocean general circulation model
 - Zonally-averaged atmospheric model
 - Thermodynamic sea-ice model
 - Simplified models for river runoff
- **Input parameters**
 - Rate of CO_2 increase (r)
 - Climate sensitivity (λ)
- **Output observable**
 - Overturning streamfunction (Z)



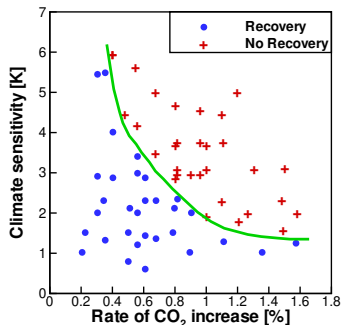
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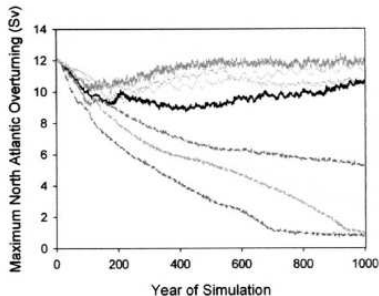
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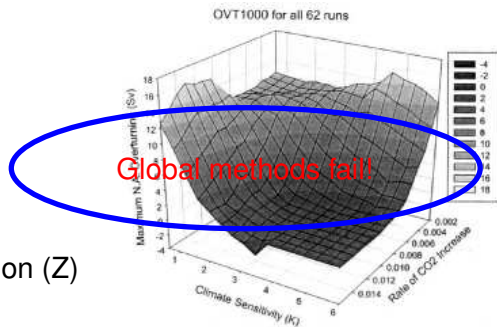
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UQ & Discontinuities - Proposed Methodology

Our approach locates the discontinuity first so the domain can be subdivided into regions with smooth model response where spectral uncertainty quantification methods can be used

- Need to represent model output in a problem-independent fashion that takes into account the bifurcations
 - **Bayesian inference of the location of the discontinuity**
- Need to perform uncertainty quantification with only a limited set of sample points, due to the computational cost of the forward model
 - **Polynomial chaos representation via parameter domain mapping**

Bayesian Inference of the Location of Discontinuity

- Parameterize the discontinuity: $r \approx p_{\mathbf{c}}(\lambda) = \sum_{k=0}^K c_k P_k(\lambda)$
- Approximation model:

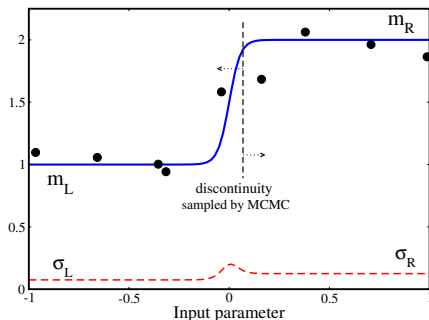
$$\mathcal{M}_{\mathbf{c}} \equiv g(\lambda, r) = m_L + (m_R - m_L) \frac{1 + \tanh(\alpha(r - p_{\mathbf{c}}(\lambda)))}{2}$$

- Noise model postulated: $\sigma(\lambda, r)$
- Likelihood function:

$$\log P(\mathcal{D} | \mathcal{M}_{\mathbf{c}}) = \sum_{i=1}^N \log (P(z_i | \mathcal{M}_{\mathbf{c}})) = - \sum_{i=1}^N \frac{(z_i - g(\lambda, r))^2}{2\sigma(\lambda, r)^2}.$$

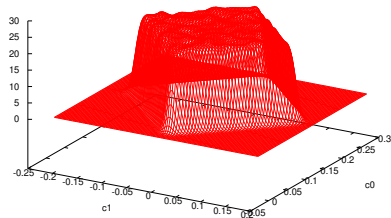
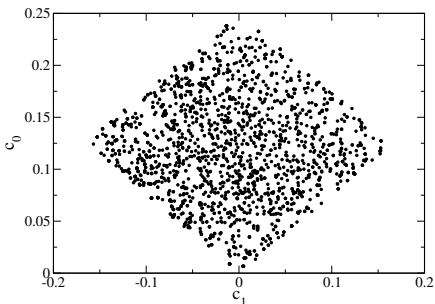
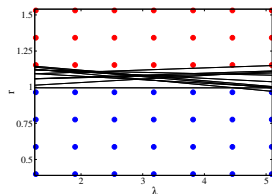
Bayesian Inference of the Location of Discontinuity

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- Bayes' formula: $P(\mathcal{M}|\mathcal{D}) = \frac{P(\mathcal{D}|\mathcal{M})P(\mathcal{M})}{P(\mathcal{D})}$



Highlights

- Any distribution of input points
- Generalizes to multiple dimensions
- Probabilistic representation



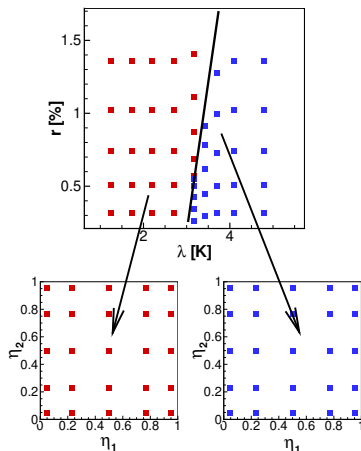
Discontinuity curve samples and their pdf

Parameter Domain Mapping

- Assume linear discontinuity
- Use Rosenblatt Transformation (RT) to map the pair of uncertain parameters (λ, r) to i.i.d. uniform random variables η_1 and η_2 :

$$\lambda = F_{\lambda}^{-1}(\eta_1),$$
$$r = F_{r|\lambda}^{-1}(\eta_2|\eta_1)$$

- Apply the RT mapping to both sides of the discontinuity



ROSENBLATT TRANSFORMATION: $(\lambda, r) \rightarrow (\eta_1, \eta_2)$

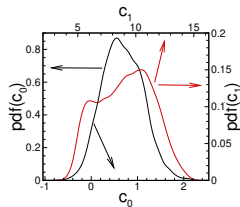
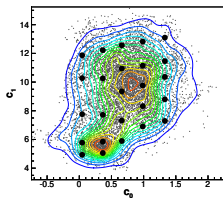
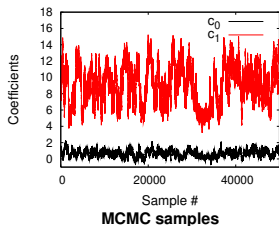
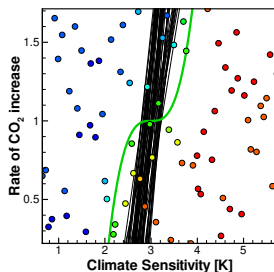
Inference of Discontinuity - 3rd order polynomial

- Synthetic discontinuous data

$$z_i = (1 + \sigma\xi)\text{erf}(\beta(r_i - \tilde{r}(\lambda_i))).$$

- Use straight lines to infer the discontinuity

$$\tilde{r}(\lambda) = c_0 + c_1\lambda.$$



Joint and Marginal Posterior Distributions

PC expansion, averaged over discontinuity curves

- PC expansion for each discontinuity curve sample:

$$Z_{\mathbf{c}}^{L,R}(\lambda, r) = \tilde{Z}_{\mathbf{c}}(\eta_1, \eta_2) = \sum_{p=0}^P z_p \Psi_p^{(2)}(\eta_1, \eta_2)$$

- Model expansion depends on the parameter location:

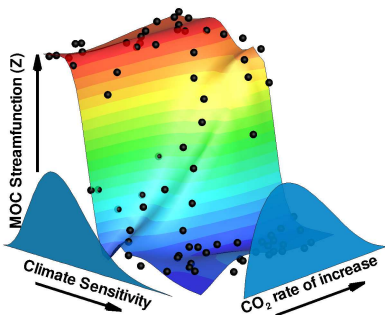
$$Z_{\mathbf{c}}(\lambda, r) = \begin{cases} Z_{\mathbf{c}}^L(\lambda, r) & \text{if } (\lambda, r) \in D_L \\ Z_{\mathbf{c}}^R(\lambda, r) & \text{if } (\lambda, r) \in D_R \end{cases}.$$

- Average over all PC expansions via RT:

$$\hat{Z}(\lambda, r) = \int_{\mathcal{C}} p(\mathbf{c}) Z_{\mathbf{c}}(\lambda, r) d\mathbf{c} = \int_{[0,1]^{K+1}} Z_{R^{-1}(\vec{\eta})}(\lambda, r) d\vec{\eta}$$

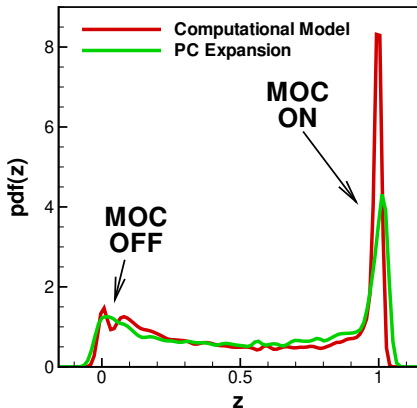
Discontinuous data represented well with the averaged PC

PCE IN (η_1, η_2) DOMAIN



Discontinuous data represented well with the averaged PC.

OUTPUT PDF



Resulting output PDF given input parameter joint PDF.

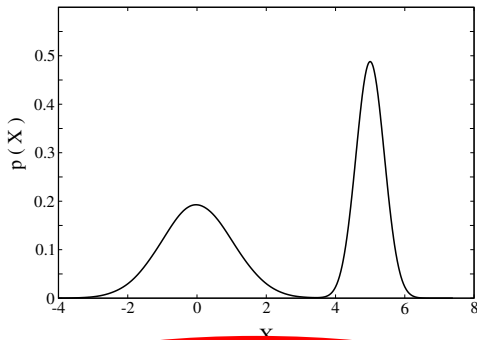
Summary

- A methodology for uncertainty quantification in climate models with limited data and discontinuities was proposed:
 - Bayesian approach to detect and parameterize the discontinuity as well as the uncertainty associated with it.
 - Rosenblatt transformation maps each of the irregular domains to rectangular ones where the application of the local spectral methods of uncertainty propagation is feasible.
- “Knowledge Discovery from Climate Data: Prediction, Extremes, and Impacts” Workshop Proceedings - 9th IEEE International Conference on Data Mining, 2009.
- Full paper in preparation.

- Bring in real climate model data.
- Still prohibitively many model runs required: possibly give up orthogonal projection in favor of Bayesian inference.
- Gaussian process emulation to implement uncertainties due to the lack of knowledge at non-sampled points.
- Experimental design: inform climate modelers on the optimal parameter sets to run simulations.

UQ methods are challenged by..

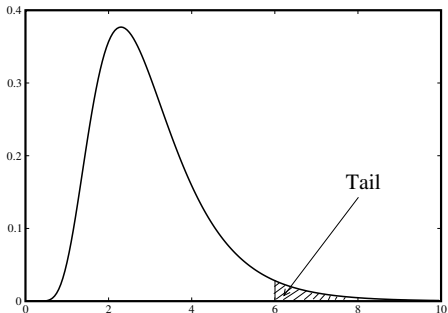
- Nonlinearities, Bifurcations, Bimodalities
- Tail regions
- Limited data
- Curse of dimensionality
- Intrinsic stochasticity



Smart domain decomposition

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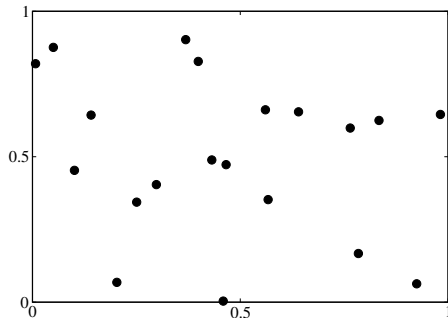
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Custom spectral bases

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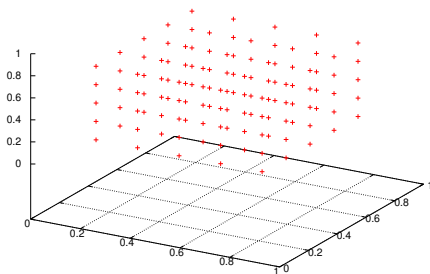
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Bayesian approach, O'Hagan's work

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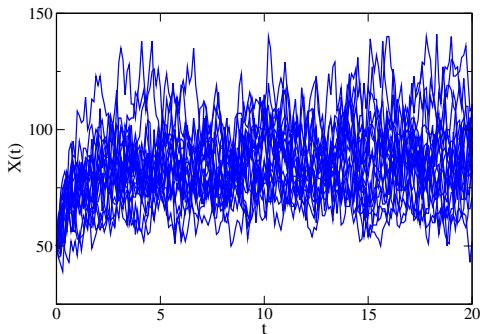
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Sparse quadrature/cubature

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Work with moments, Bayesian?

Acknowledgements

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Thank You!

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